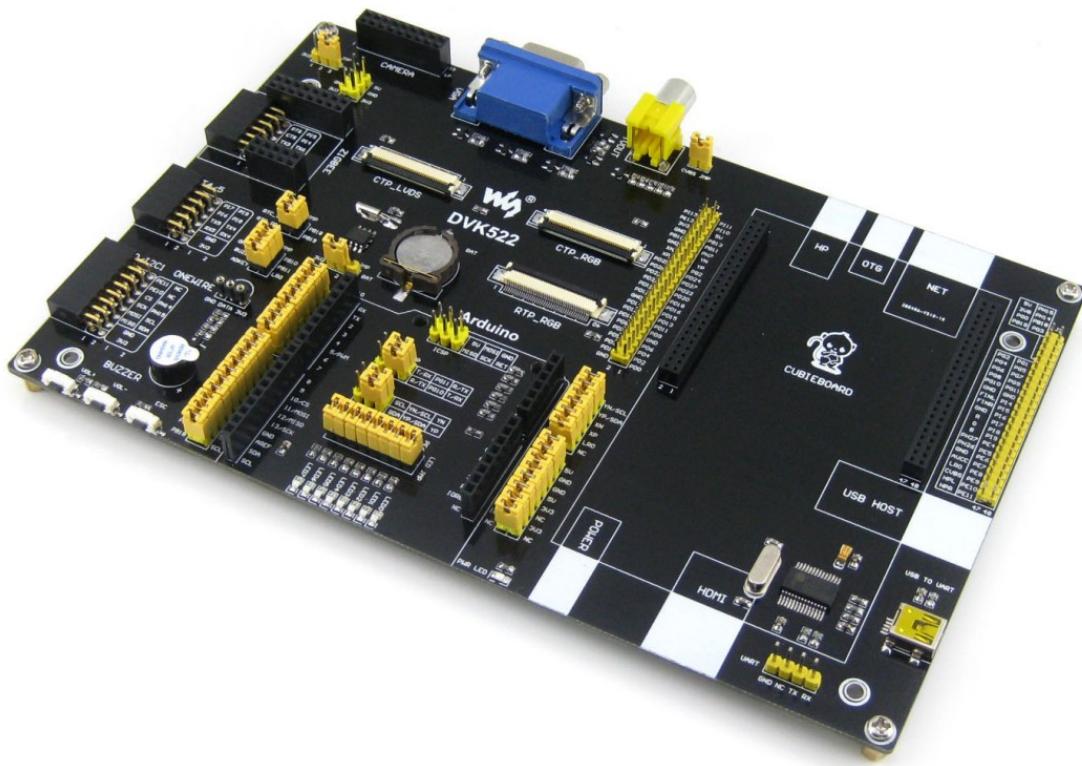


DVK522 Expansion Board

User Manual

2014.06.17 V1.1



Waveshare Electronics

www.waveshare.com

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Version update records

| Version | Date | Description |
|---------|------------|-----------------|
| V1.1 | 2014.06.17 | Initial Release |
| | | |
| | | |

Content

| | |
|--|----|
| Copyright Statement | I |
| Version update records | I |
| Document formatting convention | 1 |
| 1. Overview | 1 |
| 2. What's on board | 1 |
| 2.1. Core interface..... | 1 |
| 2.2. Component..... | 2 |
| 2.3. Jumper | 3 |
| 3. Preparation | 3 |
| 3.1 Firmware burning..... | 3 |
| 3.2 USB to serial port driver installation..... | 4 |
| 4. Starting mode..... | 5 |
| 4.1. TF Card starting | 5 |
| 4.2. Nand starting | 5 |
| 5. Type of system..... | 5 |
| 5.1 Ubuntu | 5 |
| 5.2 Debian..... | 5 |
| 6. Demos..... | 5 |
| 6.1. Display Demo | 6 |
| 6.2. LED Demo..... | 7 |
| 6.3. Buzzer Demo | 7 |
| 6.4. DS18B20 Demo | 8 |
| 6.5. AD Keypad Demo..... | 8 |
| 6.6. AT45DB Read/Write Demo..... | 9 |
| 6.7. MAG3110 Demo..... | 10 |
| 6.8. UART Interface Demo | 11 |
| 6.9. RS485 Demo | 11 |
| 6.10. GPS Demo | 13 |
| 6.11. ZIGBEE Demo..... | 13 |
| 6.12. RTC Demo | 13 |
| 6.13. USB Camera Demo | 14 |
| 6.14. WIFI Demo | 17 |

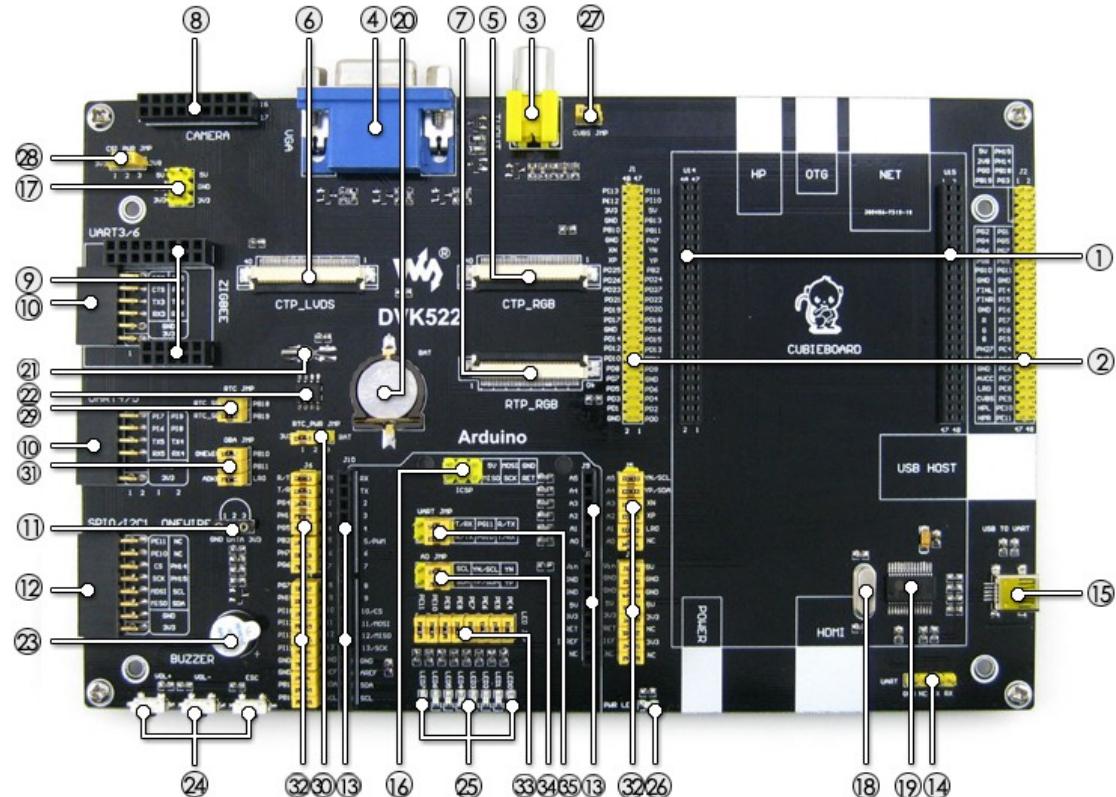
Document formatting convention

1. Commands on PC ubuntu terminal: preceding with '#', here root user privileges is requested.
Commands on the board terminal: preceding with '\$'
2. This Manual is for API demo on Ubuntu and Debian system.

1. Overview

DVK522 is an expansion board designed for Cubieboard1/2, integrates various components and interfaces for connecting external accessory boards, complete sample codes will also be offered, users can easily develop your own products with it.

2. What's on board



2.1. Core interface

- 1) CUBIEBOARD1/2 socket
for connecting CUBIEBOARD1/2

- 2) CUBIEBOARD1/2 expansion connector
For expanding IOs
- 3) TVOUT interface
video CVBS output, for connecting display devices like TV
- 4) VGA interface
for connecting VGA display Module
- 5) 7inch capacitive LCD RGB interface
for connecting 7inch capacitive LCD with RGB interface
- 6) 7inch capacitive LCD LVDS interface
for connecting 7inch capacitive LCD with LVDS interface
- 7) 7inch resistive LCD RGB interface
for connecting 7inch resistive LCD with RGB interface
- 8) CAMERA interface
for connecting OV7670 Camera Module
- 9) ZIGBEE connector
for connecting ZigBee modules like Core2530, supports working with ZB501
- 10) UART interface
easily connects to UART modules, such as RS485 Board (3.3V)、GPS module, etc.
- 11) ONEWIRE interface
easily connects to ONE-WIRE devices (TO-92 package), such as temperature sensor (DS18B20), etc.
- 12) SPI0/I2C1 interface
easily connects to SPI or I2C modules such as MAG3110 Board、AT45DBXX Dataflash, etc.
- 13) Arduino interface
for connecting compatible Arduino modules
- 14) UART interface (PL2303TA)
for connecting to UART0 interface on CUBIEBOARD1/2
- 15) USB interface
USB TO UART (PL2303TA)
- 16) ICSP interface
ICSP interface for Arduino
- 17) 5V/3.3V power input/output
usually used as power output, also common-grounding with other user board

2.2. Component

- 18) 12M crystal
for PL2303TA

- 19) PL2303TA
USB TO UART MCU
- 20) RTC backup battery
3.3V battery
- 21) 32.768KHZ crystal
for PCF8563
- 22) PCF8563
RTC board MCU
- 23) Buzzer
- 24) AD keys
3 common Android keys:
VOL+、VOL-、ESC
- 25) User LED
- 26) 8 user LEDs
- 26) Power indicator

2.3. Jumper

- 27) TVOUT selection jumper
- 28) CAMERA power selection jumper
- 29) RTC selection jumper
- 30) RTC power selection jumper
- 31) ONEWIRE、buzzer and AD key selection jumper
- 32) Arduino Port selection jumper
easily controlling the Arduino connection
- 33) User LED selection jumper
- 34) Arduino AD selection jumper
short the right: while connecting Arduino ADC shield;
short the left: while connecting Arduino I2C shield.
- 35) Arduino UART selection jumper
short the right: while connecting Arduino UART shield
short the left: while connecting Arduino microcontroller board

3. Preparation

3.1 Firmware burning

Burning corresponding firmware: cbx-dvk-xxxx.img is needed when testing DVK522 , download it from :

<http://dl.cubieboard.org/parteners/waveshare/Image/>,
detail please refer to “Burning Firmware”.

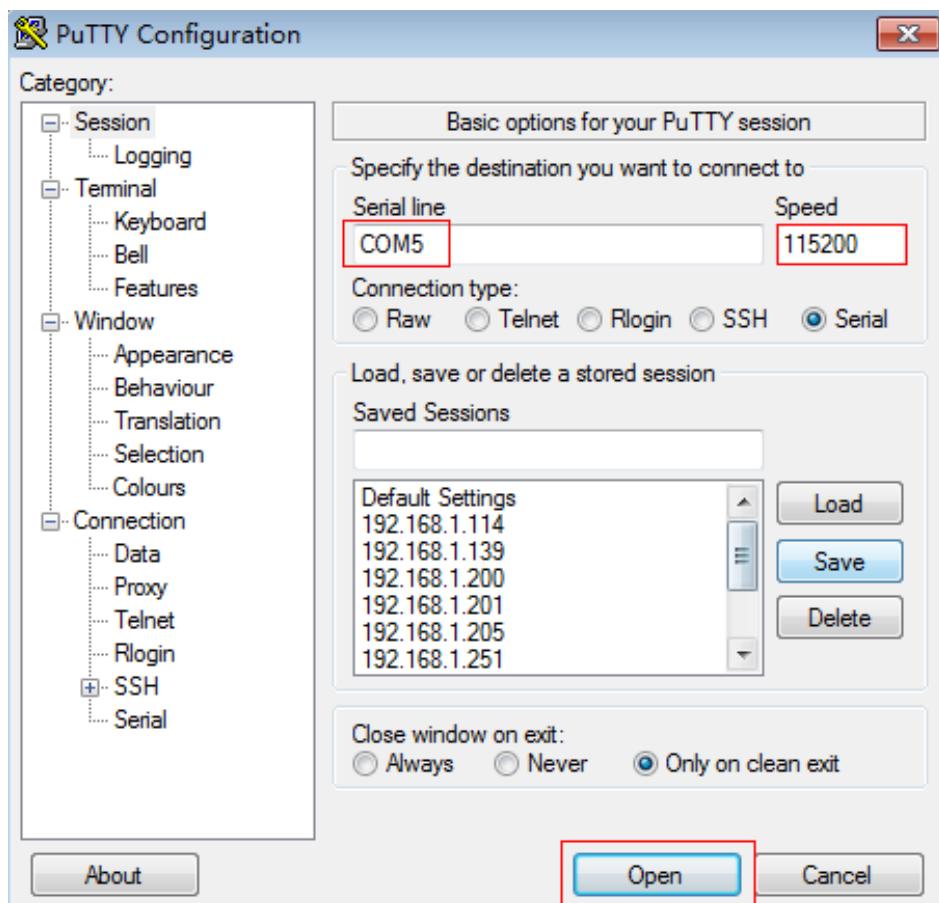
Note:

1. Note: Firmware with “sdcard” marking is TF card firmware; with “nand” marking is nand firmware.
2. Firmware version of v1.1 or above is suitable for testing DVK522, version v1.0 is compatible for old version DVK521.

3.2 USB to serial port driver installation

Connect UART connector of DVK522 to UART0 connector of cubieboard 1/2 via 4-pin or 2-pin wires, connect USB TO UART connector of DVK522 to PC via mini USB wire.

Launch **PL2303_Prolific_DriverInstaller_v1.8.0.exe** to install the driver. After installed, launch the serial debugging assistant and check putty.exe, configure like below, then click “open”.



Note: Check your computer’s “Device Manager” to see what the COM is.

4. Starting mode

4.1. TF Card starting

Insert the burned firmware TF card to the DATA CARD slot of the Cubieboard1/2, connect to electricity for starting.

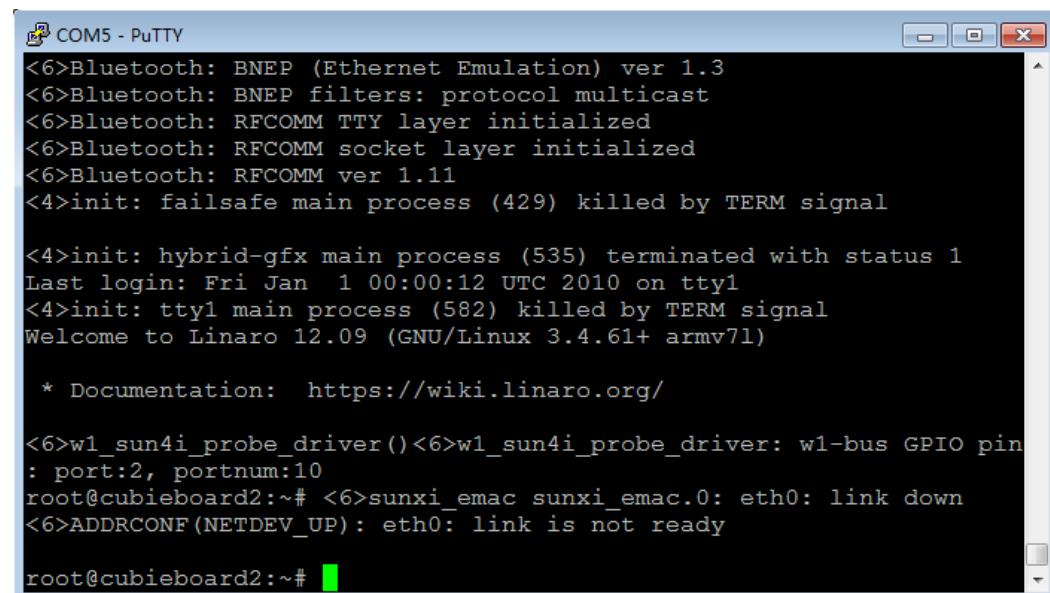
4.2. Nand starting

After burned firmware, connect to electricity for starting directly.

5. Type of system

5.1 Ubuntu

Input "enter" at the terminal to enter Bash Shell development environment with root user privileges.



```
<6>Bluetooth: BNEP (Ethernet Emulation) ver 1.3
<6>Bluetooth: BNEP filters: protocol multicast
<6>Bluetooth: RFCOMM TTY layer initialized
<6>Bluetooth: RFCOMM socket layer initialized
<6>Bluetooth: RFCOMM ver 1.11
<4>init: failsafe main process (429) killed by TERM signal

<4>init: hybrid-gfx main process (535) terminated with status 1
Last login: Fri Jan  1 00:00:12 UTC 2010 on tty1
<4>init: tty1 main process (582) killed by TERM signal
Welcome to Linaro 12.09 (GNU/Linux 3.4.61+ armv7l)

 * Documentation:  https://wiki.linaro.org/

<6>w1_sun4i_probe_driver()<6>w1_sun4i_probe_driver: w1-bus GPIO pin
: port:2, portnum:10
root@cubieboard2:~# <6>sunxi_emac sunxi_emac.0: eth0: link down
<6>ADDRCONF(NETDEV_UP): eth0: link is not ready
root@cubieboard2:~#
```

5.2 Debian

Reboot the system, input user name and password:

User:**root**

Password:**123456**

Then enter Bash Shell development environment with root user privileges.

Note: If it is not root user privilege, switch to root user !

6. Demos

Note:

1. Ensure the system firmware is provided by us, otherwise the test could not be operated!

2. Reboot the system, find all the testing sample under root of /home/waveshare_demo/API.

6.1. Display Demo

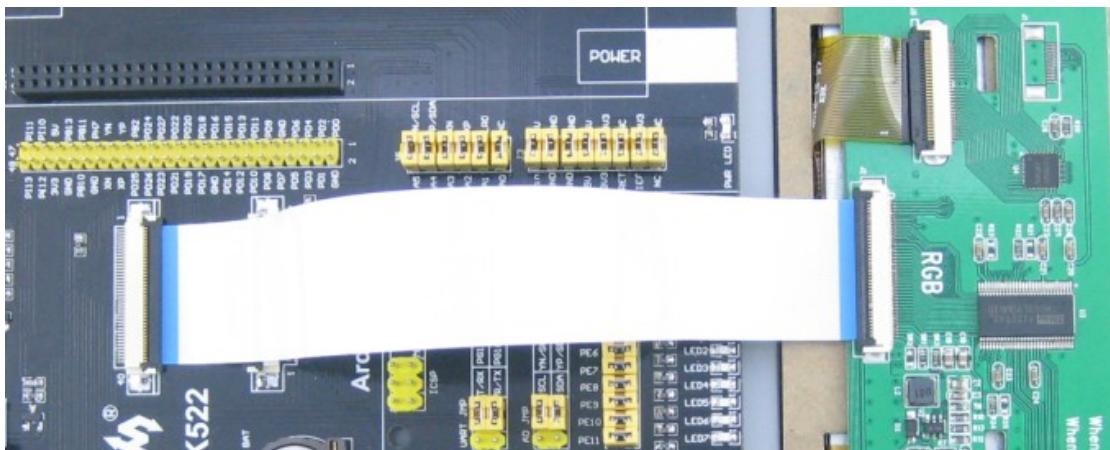
Different display demo must use corresponding firmware!

1) LCD demo

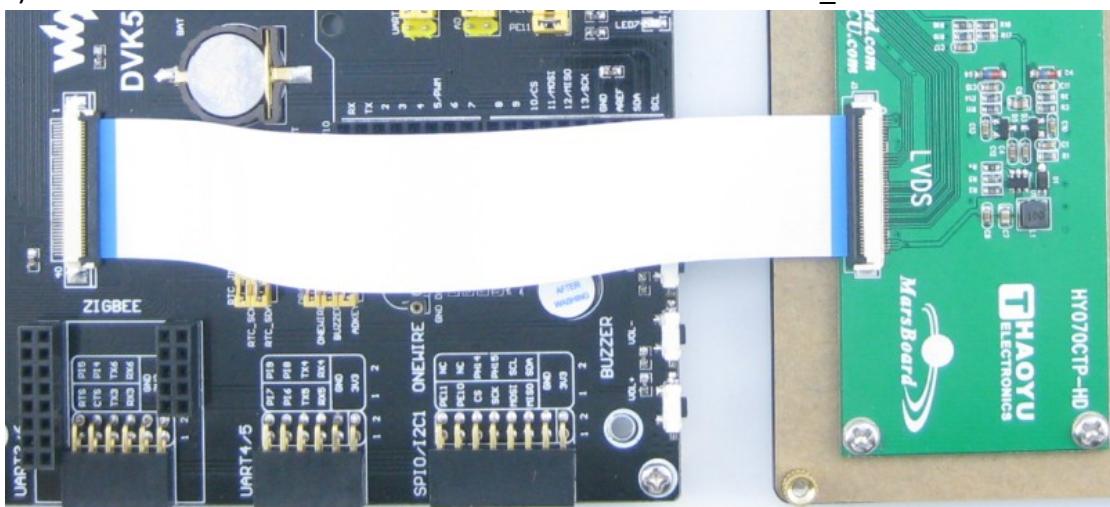
Connect connector of LCD to connector of DVK522 via 40pin wires like below:

| LCD (connector) | DVK522 (connector) |
|-----------------|--------------------|
| RGB | CTP_RGB |
| LVDS | CTP_LVDS |

a) Connect the RGB connector on the LCD to DVK522 via CTP_RGB connector :



b) Connect the LVDS connector on the LCD to DVK522 via CTP_LVDS connector :



Note:

Our standard 7" TFT LCD is capacitive touch screen, the controller is FT5X06, resolution is 1024x600, with RGB and LVDS connector.

It requests to make hardware configuration on LCD board(detail please check on

back side of the LCD board) when using different connector:

- 1) RGB connector: R24=10K, R25=NC, the 40PIN FFC connect to the RGB connector;
- 2) LVDS connector: R24=NC, R25=10K, the 40PIN FFC connect to the LVDS connector.

Default is RGB conector.

2) VGA demo

Connect the display LCD to the DVK522 onboard VGA connector via VGA wire.

3) HDMI demo

Connect the display to the cubieboard1/2 onboard HDMI connector via HDMI wire.

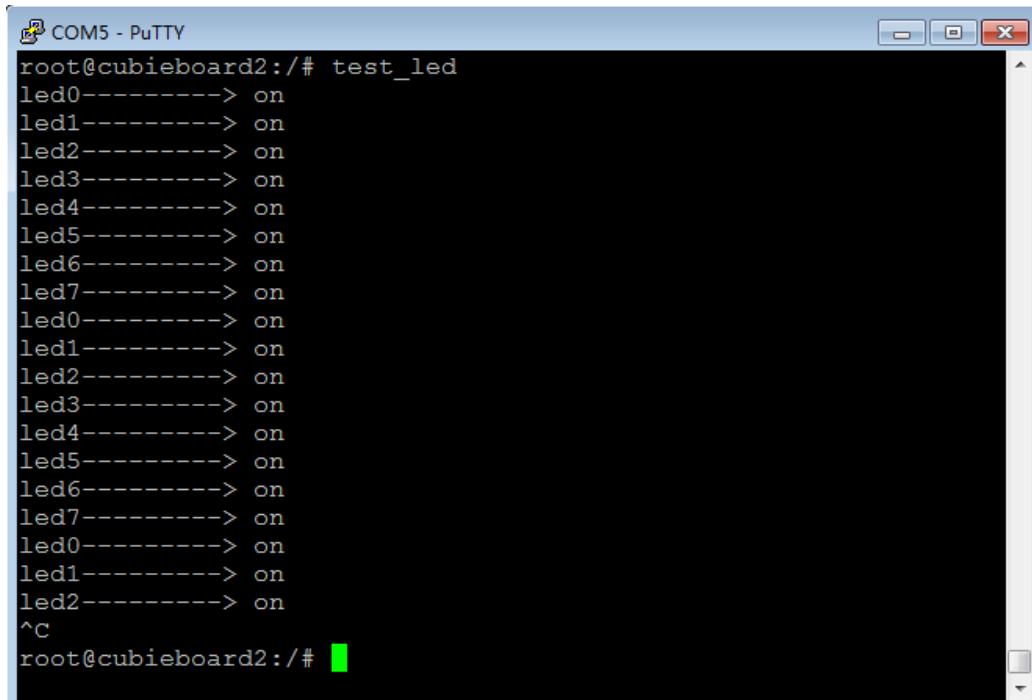
6.2. LED Demo

Short the onboard LED jumper (set by default, following are the same)

Enter the following command:

`$ test_led`

8 leds blinking:



```
root@cubieboard2:/# test_led
led0-----> on
led1-----> on
led2-----> on
led3-----> on
led4-----> on
led5-----> on
led6-----> on
led7-----> on
led0-----> on
led1-----> on
led2-----> on
led3-----> on
led4-----> on
led5-----> on
led6-----> on
led7-----> on
led0-----> on
led1-----> on
led2-----> on
^C
root@cubieboard2:/#
```

Press “Ctrl+C” to stop.

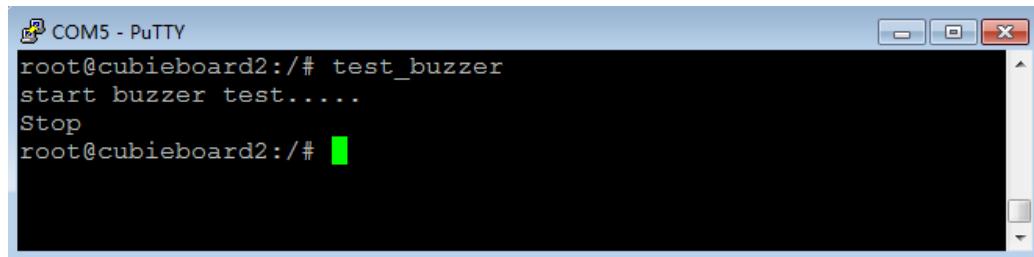
6.3. Buzzer Demo

Short the onboard BUZZER jumper

Enter the following command:

\$test_buzzer

The buzzer will start to make sound.



```
COM5 - PuTTY
root@cubieboard2:/# test_buzzer
start buzzer test.....  
Stop  
root@cubieboard2:/#
```

6.4. DS18B20 Demo

Insert the DS18B20 into the ONEWIRE socket, short the onboard ONEWIRE jumper

Enter the following command:

\$ls /sys/bus/w1/devices/

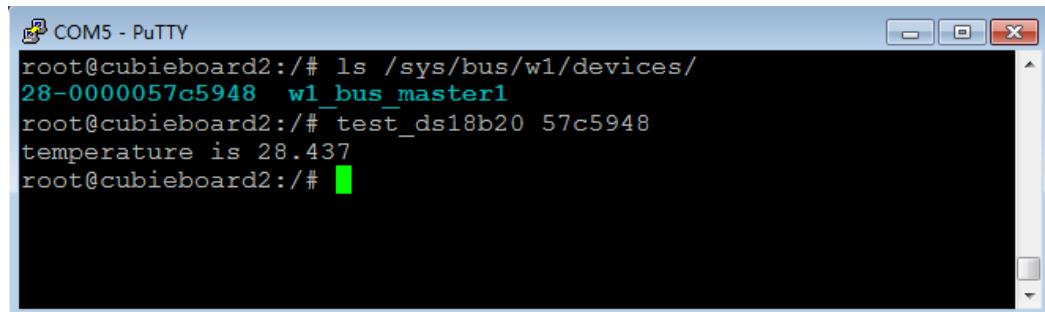
There's a folder with the name looks like "28-0000054a5bec " (the last 7 characters is an unique device ID of every different DS18B20, in this case, the device ID is 57c5948)

Enter the following command:

\$test_ds18b20 57c5948

The current environment temperature will be printed on the console terminal.

As shown in the figure below:



```
COM5 - PuTTY
root@cubieboard2:/# ls /sys/bus/w1/devices/
28-0000057c5948  w1_bus_master1
root@cubieboard2:/# test_ds18b20 57c5948
temperature is 28.437
root@cubieboard2:/#
```

6.5. AD Keypad Demo

Short the ADKEY jumper

Enter the following command:

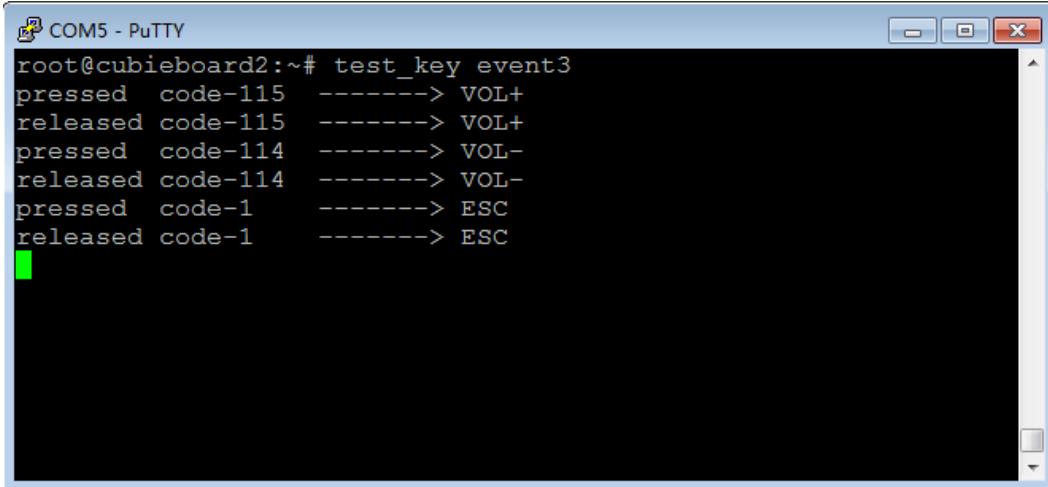
\$ test_key event3

Note:

1.What the event* is depended on the actual situation, please check directory "/dev/input";

2. Please perform: modprobe sun4i-keyboard and put sun4i-keyboard into listing /etc/modules if the keypad driver is not insmod.

Press 3 keypads respectively, then related key value that were pressed or released will be displayed on the console terminal:



```
root@cubieboard2:~# test_key event3
pressed code-115 -----> VOL+
released code-115 -----> VOL+
pressed code-114 -----> VOL-
released code-114 -----> VOL-
pressed code-1 -----> ESC
released code-1 -----> ESC
```

Press “Ctrl+C” to stop.

6.6. AT45DB Read/Write Demo

Connect the AT45DBXX DataFlash Board to the onboard SPI0 interface
Enter the following command:

\$ test_at45db

Data written and read will be displayed on the console terminal:

```

COM5 - PuTTY
root@cubieboard2:~# test_at45db
spi mode: 3
bits per word: 8
max speed: 20000000 Hz (20000 KHz)
>>>>>>Start to write [0-255]<<<<<<
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 2
2 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41
42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61
62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81
82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100
101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116
117 118 119 120 121 122 123 124 125 126 127 128 129 130 131 132
133 134 135 136 137 138 139 140 141 142 143 144 145 146 147 14
8 149 150 151 152 153 154 155 156 157 158 159 160 161 162 163 1
64 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179
180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195
196 197 198 199 200 201 202 203 204 205 206 207 208 209 210 211
212 213 214 215 216 217 218 219 220 221 222 223 224 225 226 22
7 228 229 230 231 232 233 234 235 236 237 238 239 240 241 242 2
43 244 245 246 247 248 249 250 251 252 253 254 255
>>>>>>Start to read [0-255]<<<<<<
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 2
2 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41
42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61
62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81
82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100
101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116
117 118 119 120 121 122 123 124 125 126 127 128 129 130 131 132
133 134 135 136 137 138 139 140 141 142 143 144 145 146 147 14
8 149 150 151 152 153 154 155 156 157 158 159 160 161 162 163 1
64 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179
180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195
196 197 198 199 200 201 202 203 204 205 206 207 208 209 210 211
212 213 214 215 216 217 218 219 220 221 222 223 224 225 226 22
7 228 229 230 231 232 233 234 235 236 237 238 239 240 241 242 2
43 244 245 246 247 248 249 250 251 252 253 254 255
root@cubieboard2:~#

```

6.7. MAG3110 Demo

Connect the MAG3110 Board to the onboard I2C1 interface,

Enter the following command:

\$test_mag3110

Rotate the module for a circle in the same plane to record the maximum and minimum mean parameter. When the correction finished, the correct guide angle will be displayed on the console terminal:

```

COM5 - PuTTY
root@cubieboard2:~# test_mag3110
turn a lap to adjust global variable..
Point to the south angle 225°

```

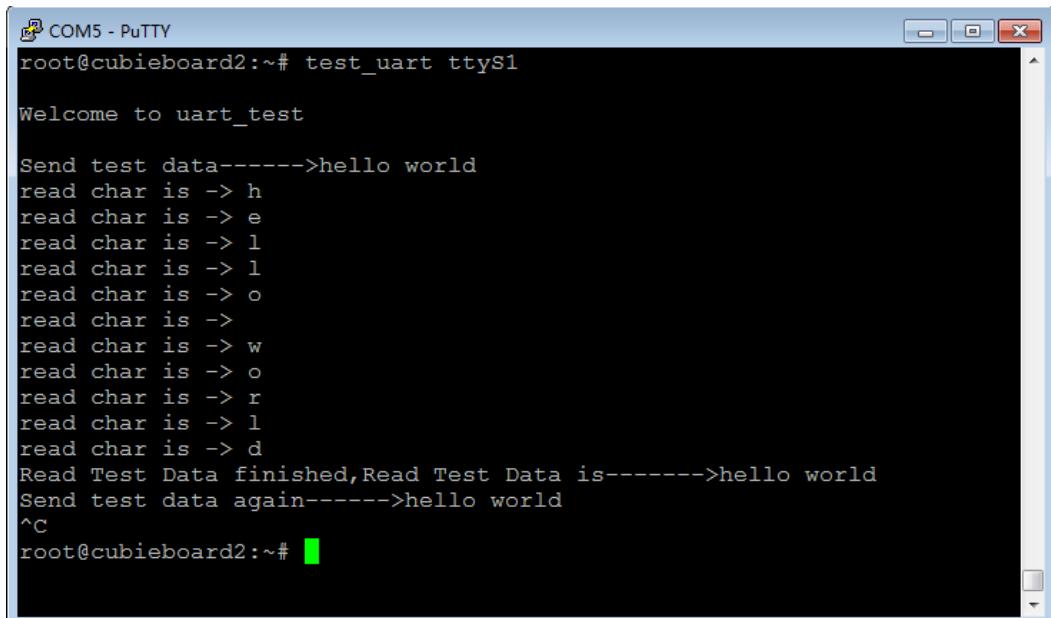
Press “Ctrl+C” to stop.

6.8. UART Interface Demo

Short RXD and TXD of the UART

Enter the following command:

```
$ test_uart ttyS1
```



```
COM5 - PuTTY
root@cubieboard2:~# test_uart ttyS1
Welcome to uart_test

Send test data----->hello world
read char is -> h
read char is -> e
read char is -> l
read char is -> l
read char is -> o
read char is ->
read char is -> w
read char is -> o
read char is -> r
read char is -> l
read char is -> d
Read Test Data finished, Read Test Data is----->hello world
Send test data again----->hello world
^C
root@cubieboard2:~#
```

If the serial port can receive and send automatically, it means the UART can work normally.

Note:

UART3 interface corresponds to ttyS1,
UART4 interface corresponds to ttyS2,

6.9. RS485 Demo

Connect the two RS485 Boards to the onboard UART3 and UART4 interface. Connect the A, B side of one RS485 module to the A, B side of the other RS485 module using connecting wires. Users can also use their own RS485 for testing.

The two RS485 devices can optionally regarded as a receiver or transmitter, the receiver should firstly be in receiving status, then the transmitter begin to send.

Open two console terminals, one enter the following command:

```
$ test_485_uart3 -d /dev/ttyS1 -b 115200
```

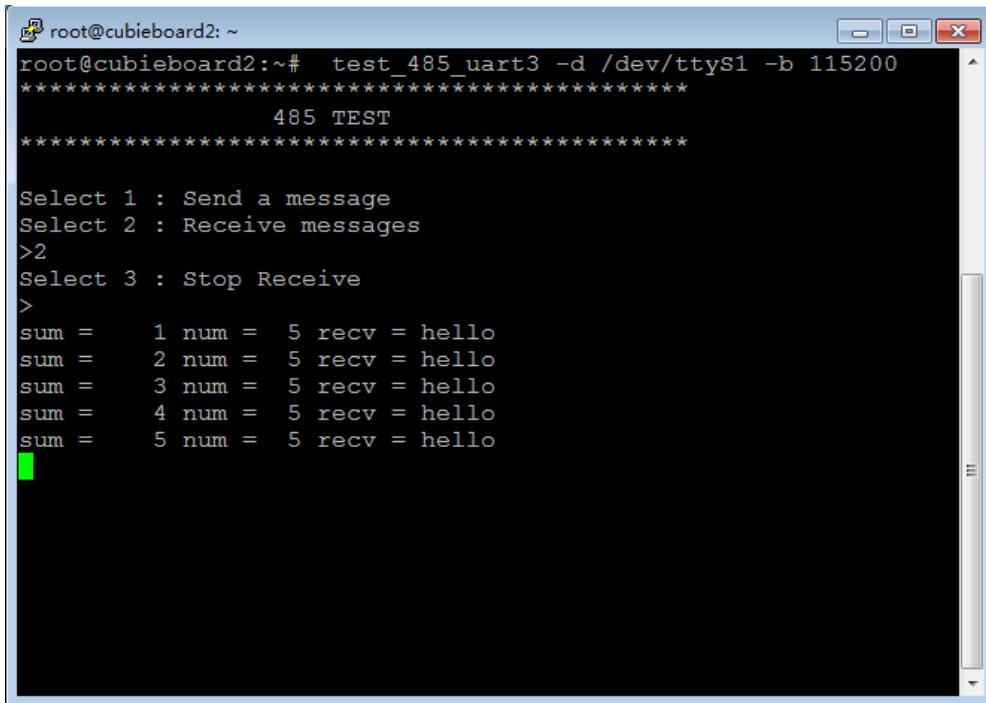
The other enter the following command:

```
$ test_485_uart4 -d /dev/ttyS2 -b 115200
```

- 1) Select "2" for the receiver, before select "3" to stop receiving, the receiver remain

in the status of receiving ,

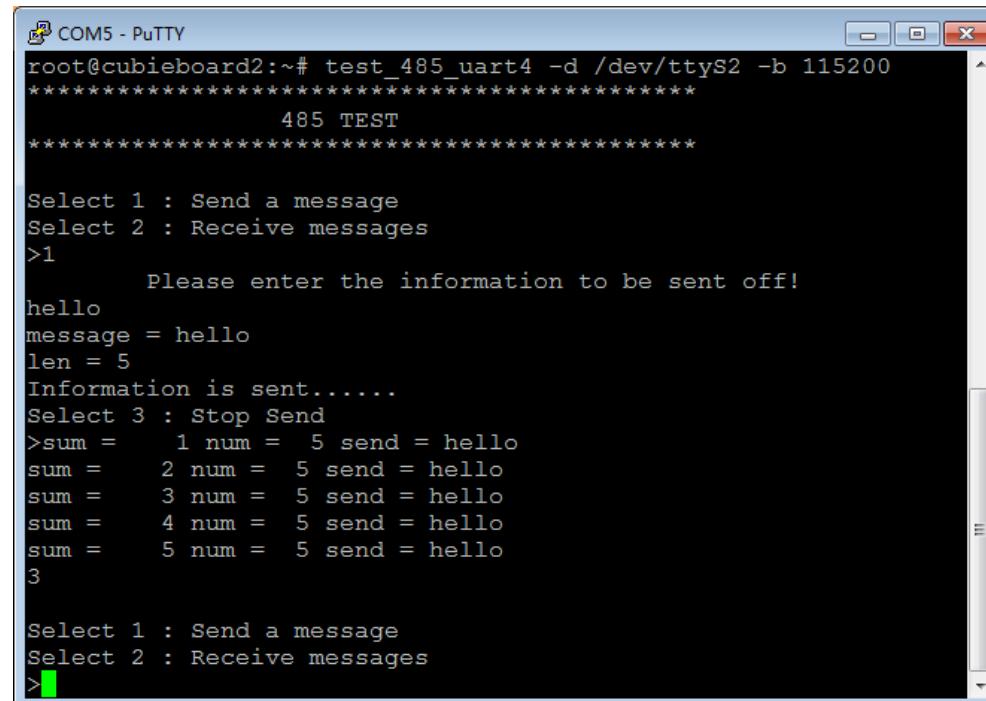
As shown in the figure below:



```
root@cubieboard2:~# test_485_uart3 -d /dev/ttys1 -b 115200
*****
485 TEST
*****
Select 1 : Send a message
Select 2 : Receive messages
>2
Select 3 : Stop Receive
>
sum = 1 num = 5 recv = hello
sum = 2 num = 5 recv = hello
sum = 3 num = 5 recv = hello
sum = 4 num = 5 recv = hello
sum = 5 num = 5 recv = hello
```

- 2) Select "1" for the receiver, enter information that you want to send, such as "hello", before select "3" to stop sending, the transmitter remain in the status of loop sending, keep sending data,

As shown in the figure below:



```
root@cubieboard2:~# test_485_uart4 -d /dev/ttys2 -b 115200
*****
485 TEST
*****
Select 1 : Send a message
Select 2 : Receive messages
>1
      Please enter the information to be sent off!
hello
message = hello
len = 5
Information is sent......
Select 3 : Stop Send
>sum = 1 num = 5 send = hello
sum = 2 num = 5 send = hello
sum = 3 num = 5 send = hello
sum = 4 num = 5 send = hello
sum = 5 num = 5 send = hello
3

Select 1 : Send a message
Select 2 : Receive messages
>
```

Press Ctrl+C to stop.

6.10. GPS Demo

Connect the UART GPS module to the onboard UART3 interface,
Enter the following command:

Note:

1.The GPS module demo must be operated outdoor, otherwise it can not receive the satellite data.

2.The testing program is compatible with GPS module with baud rate 9600.

`$ test_gps ttyS1`

User can analyze corresponding data according to their needs. Press Ctrl+C to stop.

Detail for how to use the UART GPS module please refer to:

<http://www.waveshare.com/aspx/search.aspx?keywords=GPS>

6.11. ZIGBEE Demo

Interface of onboard ZIGBEE only compatible with configured Core2530 board.
When burning program for the core board or other corresponding configure, it may need support from ZB501. Detail development package please refer to:
<http://www.waveshare.com/product/ZB501.htm>

6.12. RTC Demo

Test onboard DVK522 RTC, enter corresponding demand on the console terminal:

Note:

This demo must be sure to use button battery, that is short RTC_PWR JMP to "2-3", BAT side.

1) Add device:

`$ echo pcf8563 0x51 > /sys/class/i2c-adapter/i2c-1/new_device`

Note:

Please execute: modprobe rtc-pcf8563 if RTC driver did not load and add rtc-pcf8563 to the list of /etc/modules

2) Read the system time

`$ date`

3) Configure the system time:

`$ date 061717502014.23`

4) Set the hardware of RTC time:

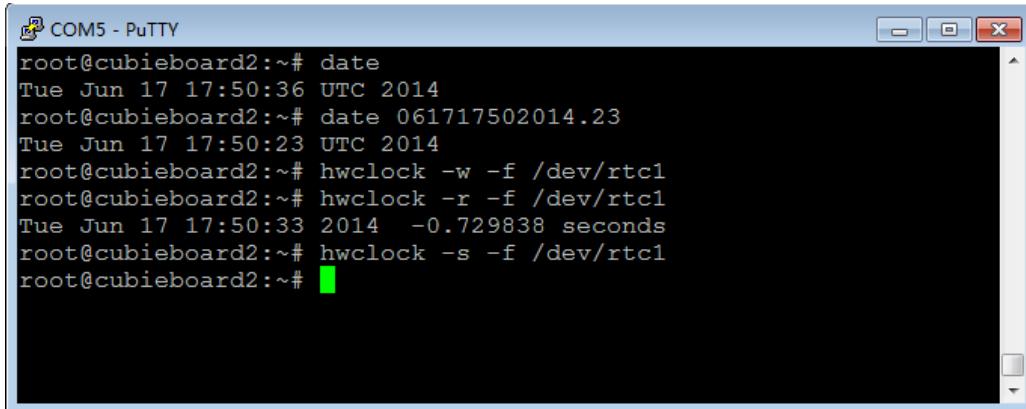
`$ hwclock -w -f /dev/rtc1`

5) Read time of RTC hardware:

`$ hwclock -r -f /dev/rtc1`

6) Time of RTC hardware synchronized to the system time:

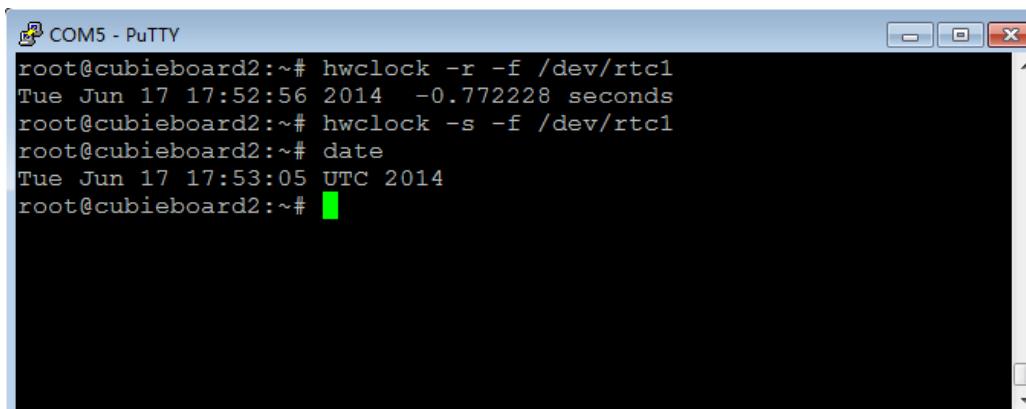
`$ hwclock -s -f /dev/rtc1`



```
COM5 - PuTTY
root@cubieboard2:~# date
Tue Jun 17 17:50:36 UTC 2014
root@cubieboard2:~# date 061717502014.23
Tue Jun 17 17:50:23 UTC 2014
root@cubieboard2:~# hwclock -w -f /dev/rtc1
root@cubieboard2:~# hwclock -r -f /dev/rtc1
Tue Jun 17 17:50:33 2014 -0.729838 seconds
root@cubieboard2:~# hwclock -s -f /dev/rtc1
root@cubieboard2:~#
```

- 7) Cut off the power and restart, read the time of RTC hardware and synchronized to the system time, enter the following command:

```
$ echo pcf8563 0x51 > /sys/class/i2c-adapter/i2c-1/new_device
$ hwclock -r -f /dev/rtc1
$ hwclock -s -f /dev/rtc1
$ date
```



```
COM5 - PuTTY
root@cubieboard2:~# hwclock -r -f /dev/rtc1
Tue Jun 17 17:52:56 2014 -0.772228 seconds
root@cubieboard2:~# hwclock -s -f /dev/rtc1
root@cubieboard2:~# date
Tue Jun 17 17:53:05 UTC 2014
root@cubieboard2:~#
```

Now, time of the software and hardware are synchronized, the RTC works normally.

6.13. USB Camera Demo

Connect our standard USB Camera to the onboard Cubieboard1/2 USB Host interface, connect the network cable(to ensure access to the Internet), enter corresponding command:

Note: Users can directly start from step 5) as the firmware we provided already finished step 1)- step 4).

- 1) Install corresponding tool

```
$apt-get install libv4l-dev
$apt-get install libjpeg8-dev
$apt-get install subversion
$apt-get install imagemagick
$apt-get install make
$apt-get install vim
```

- 2) Download mjpg-streamer source code

```
$cd /  
$svn co https://svn.code.sf.net/p/mjpg-streamer/code/ mjpg-streamer
```

It will download automatically after executed the command, after finish download, the mjpg-streamer document will appeared in the current directory.

- 3) Modify the configuration file

```
$vi mjpg-streamer/mjpg-streamer/plugins/input_uvc/input_uvc.c
```

Modify:

```
int width = 640, height = 480, fps = 5, format = V4L2_PIX_FMT_MJPEG, i;
```

to:

```
int width = 320, height = 240, fps = 5, format = V4L2_PIX_FMT_YUYV, i;
```

Exit after save it.

- 4) Compile

```
$cd /mjpg-streamer/mjpg-streamer
```

```
$make clean
```

```
$make
```

- 5) Check the assigned ip address:

```
$ ifconfig eth0
```

```
root@cubieboard2:~# ifconfig eth0  
eth0      Link encap:Ethernet HWaddr 02:15:04:c3:03:90  
          inet addr:192.168.1.244 Bcast:192.168.1.255 Mask:255.  
          255.255.0  
          inet6 addr: fe80::15:4ff:fec3:390/64 Scope:Link  
            UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1  
            RX packets:1267 errors:0 dropped:0 overruns:0 frame:0  
            TX packets:115 errors:0 dropped:0 overruns:0 carrier:0  
            collisions:0 txqueuelen:1000  
            RX bytes:159382 (159.3 KB) TX bytes:14401 (14.4 KB)  
            Interrupt:87 Base address:0xa000  
  
root@cubieboard2:~#
```

The ip address is 192.168.1.244.

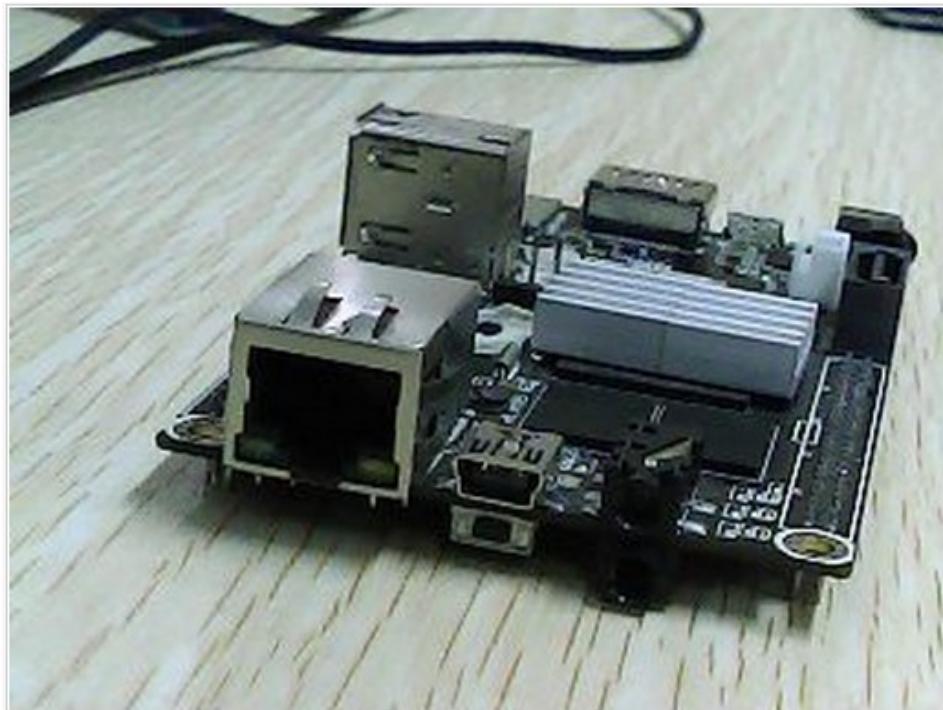
- 6) Check the assigned ip address:

```
$cd /mjpg-streamer/mjpg-streamer
```

```
$ ./start.sh
```

```
COM5 - PuTTY
Adding control for Tilt Reset
UVCIOC_CTRL_ADD - Error: Inappropriate ioctl for device
Adding control for Pan/tilt Reset
UVCIOC_CTRL_ADD - Error: Inappropriate ioctl for device
Adding control for Focus (absolute)
UVCIOC_CTRL_ADD - Error: Inappropriate ioctl for device
mapping control for Pan (relative)
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Tilt (relative)
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Pan Reset
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Tilt Reset
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Pan/tilt Reset
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Focus (absolute)
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for LED1 Mode
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for LED1 Frequency
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Disable video processing
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
mapping control for Raw bits per pixel
UVCIOC_CTRL_MAP - Error: Inappropriate ioctl for device
o: www-folder-path....: ./www/
o: HTTP TCP port.....: 8080
o: username:password.: disabled
o: commands.....: enabled
```

- 7) Open the browser on a computer which is connected to the same subnet(or directly on the LCD display which is connected to DVK522), enter the following address: <http://192.168.1.244:8080/javascript.html>
You can see the captured video stream. Press Ctrl+C to stop.



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6.14. WIFI Demo

Insert our standard USB WIFI to the Cubieboard1/2 onboard USB Host connector, enter corresponding command on the console terminal:

- 1) Install corresponding tools

```
$apt-get install wifi-radar
```

```
$apt-get install linux-firmware
```

When finished, reboot the system.

- 2) After rebooted the system, turn off the Ethernet card and open WIFI card.

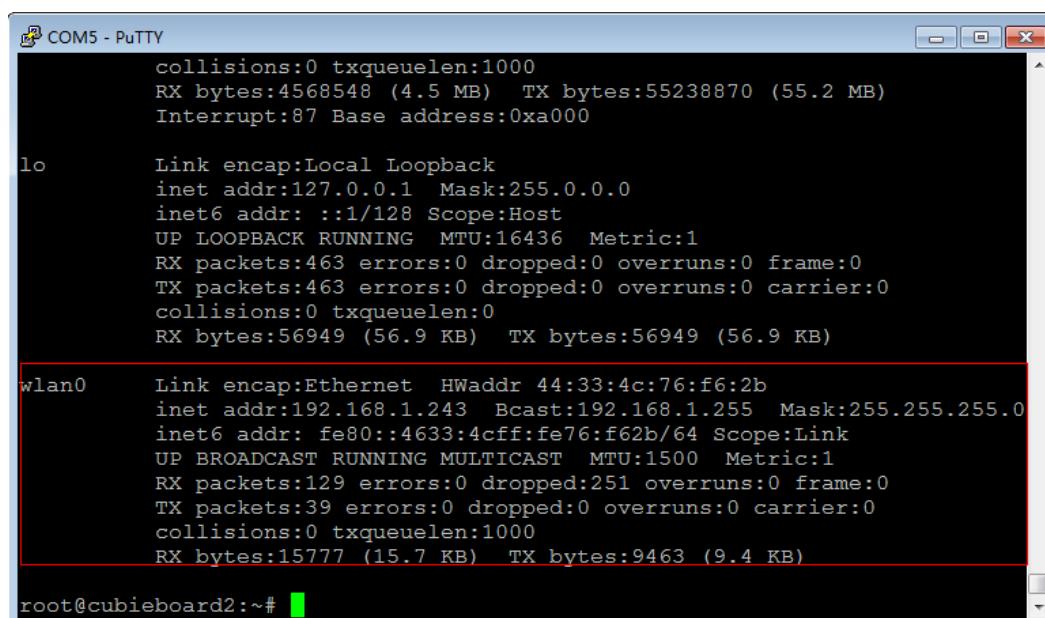
```
$ifconfig eth0 down
```

```
$ifconfig wlan0 up
```

Note: It may be "wlan1" in different system, according to the actual situation.

- 3) Check the network status:

```
$ifconfig
```



```
collisions:0 txqueuelen:1000
RX bytes:4568548 (4.5 MB) TX bytes:55238870 (55.2 MB)
Interrupt:87 Base address:0xa000

lo      Link encap:Local Loopback
        inet addr:127.0.0.1 Mask:255.0.0.0
        inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING MTU:16436 Metric:1
          RX packets:463 errors:0 dropped:0 overruns:0 frame:0
          TX packets:463 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:56949 (56.9 KB) TX bytes:56949 (56.9 KB)

wlan0   Link encap:Ethernet HWaddr 44:33:4c:76:f6:2b
        inet addr:192.168.1.243 Bcast:192.168.1.255 Mask:255.255.255.0
        inet6 addr: fe80::4633:4cff:fe76:f62b/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
          RX packets:129 errors:0 dropped:251 overruns:0 frame:0
          TX packets:39 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:15777 (15.7 KB) TX bytes:9463 (9.4 KB)

root@cubieboard2:~#
```

- 4) Scan the wireless router:

```
$iwlist wlan0 scan
```

to find available wireless network.

The screenshot shows a PuTTY window titled "COM5 - PuTTY". The terminal output displays a wireless network scan. It lists several networks, providing details such as ESSID, Protocol, Mode, Frequency, Encryption key, Bit Rates, and Extra information (RSN IE). One entry is for a network named "NETGEAR17" with an address of 2C:B0:5D:25:33:71.

```

ESSID:"HP-Print-1E-Officejet Pro 8600"
Protocol:IEEE 802.11bg
Mode:Master
Frequency:2.437 GHz (Channel 6)
Encryption key:on
Bit Rates:54 Mb/s
Extra:rsn_ie=30140100000fac040100000fac040100000fac020
000
IE: IEEE 802.11i/WPA2 Version 1
Group Cipher : CCMP
Pairwise Ciphers (1) : CCMP
Authentication Suites (1) : PSK
Quality=101/100 Signal level=-74 dBm
Cell 06 - Address: 2C:B0:5D:25:33:71
ESSID:"NETGEAR17"
Protocol:IEEE 802.11bgn
Mode:Master
Frequency:2.447 GHz (Channel 8)
Encryption key:on
Bit Rates:144 Mb/s
Extra:rsn_ie=30140100000fac040100000fac040100000fac020
c00
IE: IEEE 802.11i/WPA2 Version 1
Group Cipher : CCMP
Pairwise Ciphers (1) : CCMP
Authentication Suites (1) : PSK
IE: Unknown: DD310050F204104A000110104400010210470010F
B0548E7C1A08D76293FB64054D1CFAF103C0001031049000600372A000120
Quality=101/100 Signal level=-63 dBm
root@cubieboard2:~#

```

5) Configure wlan0:

\$vi /etc/network/interfaces

Acquire the IP configuration dynamically as following:

```
#auto lo eth0
iface lo inet loopback
iface eth0 inet dhcp
```

```
auto wlan0
iface wlan0 inet dhcp
pre-up ip link set wlan0 up
pre-up iwconfig wlan0 essid waveshareNet
wpa-ssid waveshareNet
wpa-psk 123456
```

Acquire the IP configuration statically as following:

```
#auto lo eth0
iface lo inet loopback
iface eth0 inet dhcp
```

```
auto wlan0
iface wlan0 inet static
address 192.168.1.121
```

```
netmask 255.255.255.0  
gateway 192.168.1.1  
pre-up ip link set wlan0 up  
pre-up iwconfig wlan0 essid waveshareNet  
wpa-ssid waveshareNet  
wpa-psk 123456
```

Exit after save it.

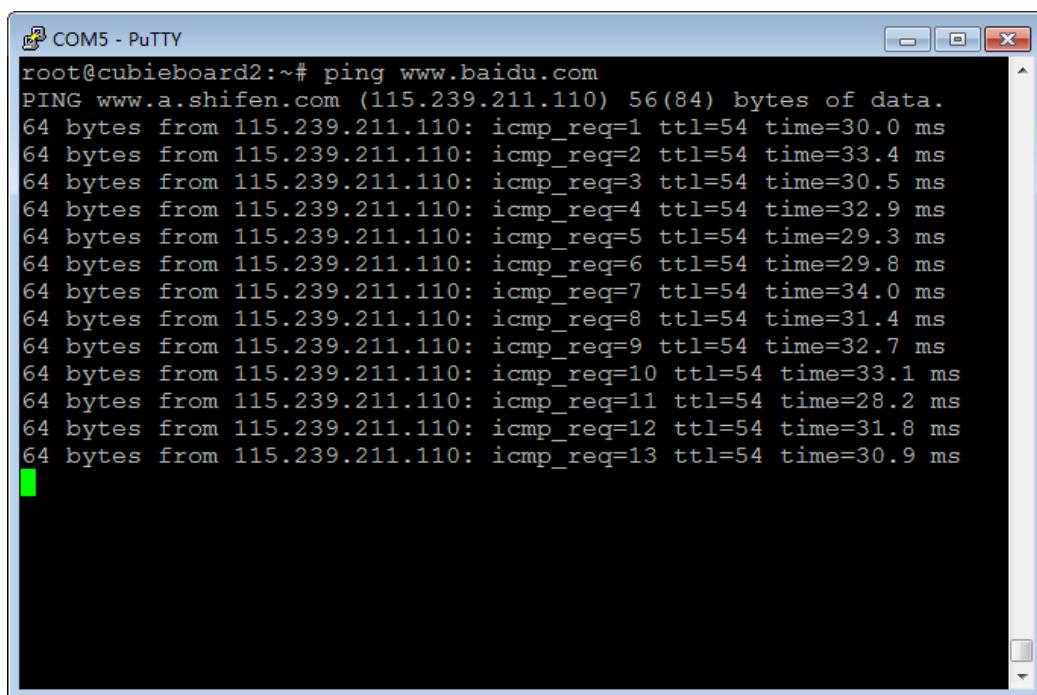
Note: Configure ESSID and PSK properly according to the scan result.

6) Restart the network:

\$/etc/init.d/networking restart

7) Restart the network:

\$ ping www.baidu.com



```
root@cubieboard2:~# ping www.baidu.com
PING www.a.shifen.com (115.239.211.110) 56(84) bytes of data.
64 bytes from 115.239.211.110: icmp_req=1 ttl=54 time=30.0 ms
64 bytes from 115.239.211.110: icmp_req=2 ttl=54 time=33.4 ms
64 bytes from 115.239.211.110: icmp_req=3 ttl=54 time=30.5 ms
64 bytes from 115.239.211.110: icmp_req=4 ttl=54 time=32.9 ms
64 bytes from 115.239.211.110: icmp_req=5 ttl=54 time=29.3 ms
64 bytes from 115.239.211.110: icmp_req=6 ttl=54 time=29.8 ms
64 bytes from 115.239.211.110: icmp_req=7 ttl=54 time=34.0 ms
64 bytes from 115.239.211.110: icmp_req=8 ttl=54 time=31.4 ms
64 bytes from 115.239.211.110: icmp_req=9 ttl=54 time=32.7 ms
64 bytes from 115.239.211.110: icmp_req=10 ttl=54 time=33.1 ms
64 bytes from 115.239.211.110: icmp_req=11 ttl=54 time=28.2 ms
64 bytes from 115.239.211.110: icmp_req=12 ttl=54 time=31.8 ms
64 bytes from 115.239.211.110: icmp_req=13 ttl=54 time=30.9 ms
```

Note:

Users can connect WIFI directly on graphical interface.