



CUBIEBOARD
<http://cubieboard.org>

DS-5 debug kernel of linux and android combine DSTREAM

ARM DS-5

Website:<http://cubieboard.org/>
Support: support@cubietech.com



Version	Author	Modification	Check
V-0.1-20150203	Payne	Init version	



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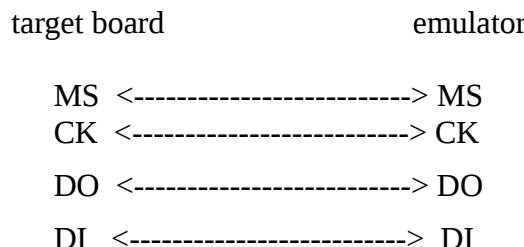
1. Equipment

- 1) PC x 1
- 2) DS-5 Software Development Tools x 1
- 3) DSTREAM Emulator x 1
- 4) Kernel development board(Take cubietruck for example) x 1
- 5) Other Cables

note: The following operate in the linux operating system which is similar to the windows system, you need to pay attention to the paths.

2. Hardware Wiring

Hardwired is very simple, PC machine and simulation connect with the usb cable. The target board and emulator just connect to the following lines except VCC and GND.



More details about DSTREAM hardware information, please visit ARM's official website:
<http://infocenter.arm.com/help/index.jsp>

About pin figure of cubieboard hardware, please visit the official website :
<http://cubieboard.org>



Attaching the picture, cubietruck and DSTREAM physical connection diagram:



3. Add a new chip to the DS-5 Debug device list

3.1. Explanation

DS-5 supports all ARM processors, but most of the processors require their own database which support the target processor. All ARM target process was imported to the database were supported by DS-5. The database can set the features of the target device flexibly. Such as trace and memory-mapped registers, can reduce the additional connection steps.

We assume installed directory on DS - 5 :/usr/local/DS-5 , If you haven't installed DS - 5, please go to the arm's official website to download: <http://ds.arm.com/downloads/>

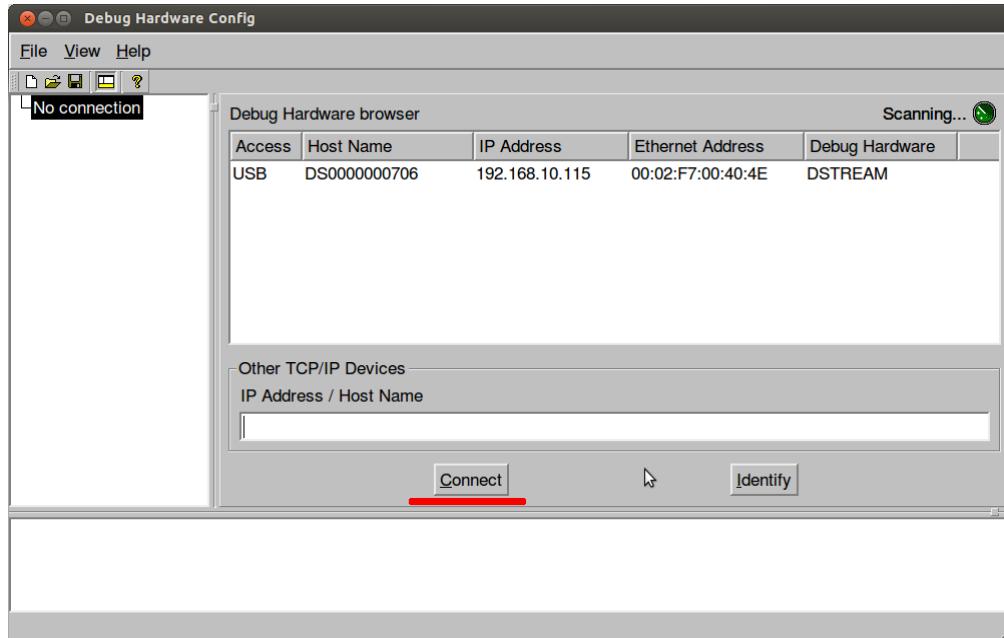
3.2. Steps

3.2.1. Create DS-5 Configuration Database

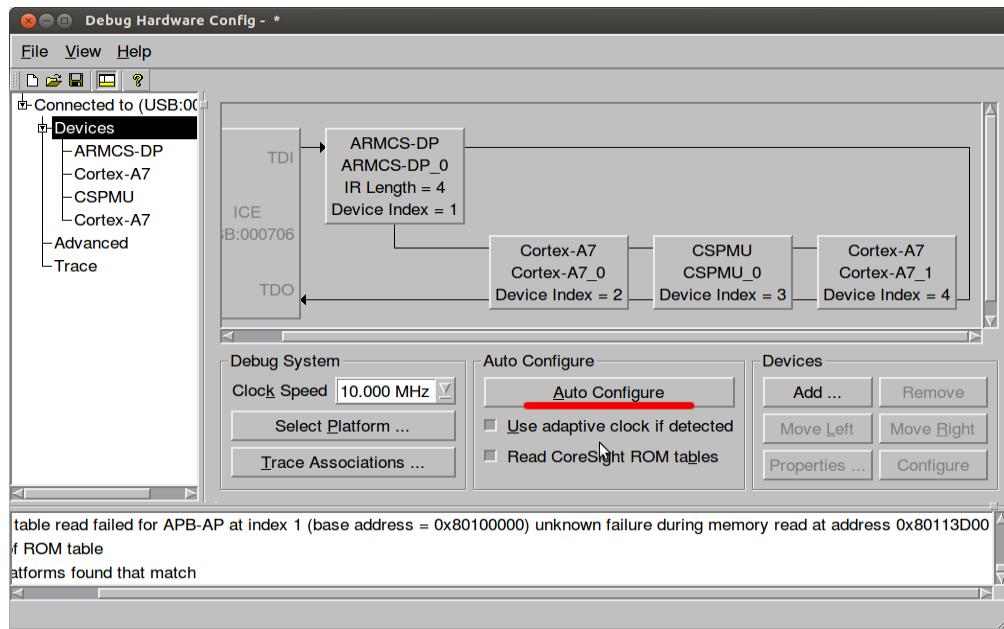
- 1) We need to connect the hardware according to the step 2, input in the terminal



\$ dbghwconfig



Selected device in the debug hardware browser, click "Connect", jump to the next step



Click on "Auto Configure" and will appear a chip information (due to the hardware characteristics, please connect the cubietruck debug serial port as well, otherwise the emulator hardly read the chip information), save the configuration information then exit.

note: Here to do special configuration for different chip ,be sure to use the configuration files of A20 chip which we offer, the above steps is how to generate configuration files, and only for reference.



A20 configuration file download address:

http://dl.cubieboard.org/developers/debug-tools/ARM-DS-5/source/AW_A7MP2NOETM.rvc

2) Generated configuration files combine dbghwconfig, run the configure database import tool, and use the appropriate parameters.

usage :**cdbimporter [-c config_db] [-t destination_db] rvc_file**

config_db: The full path of the master DS-5 configuration database

destination_db: The full path of the new configuration database

rvc_file: The full path which hardware configuration tool to generate the RVC

Example:

```
$ cdbimporter -c /usr/local/DS-5/sw/debugger/configdb -t /home/parker/cubie_configdb A20_chip.rvc
```

Select a core to modify (enter the index and hit return) or press enter to continue. [] : PRESS ENTER

Enter Platform Manufacturer
[default:'Imported'] > COMPANYX

Enter Platform Name
[default:'target'] > PLATFORMX

The files of the Import tool generated which stored in the specified target database, generated in this tutorial:

/home/parker/cubie_configdb

```
Reading /work/tools/DS-5-Workspace/configdb_Aw/Boards/AW/A7MP2NOETM/AW_A7MP2NOETM.rvc

Found 2 ARM cores
Import Summary -
ID  Name      Definition  Associated TCF files
--  --
1  Cortex-A7_0 Cortex-A7  <none>
3  Cortex-A7_1 Cortex-A7  <none>

Select a core to modify (enter its ID and hit return) or press enter to continue. []

Enter Platform Manufacturer
[default:'AW'] >

Enter Platform Name
[default:'A7MP2NOETH'] >

Building configuration XML...

Creating database entry...

Import successfully completed

The new platform will not be visible in the DS-5 Debugger until the destination database
has been added to the "User Configuration Databases" list and the database has been rebuilt.
A rebuild is done either when DS-5 is (re)started, a user configuration database is added or
by forcing a database rebuild.
To force a rebuild or add a database, select the "Window -> Preferences" menu item,
then expand the DS-5 group. To rebuild, select "Configuration Database", then press
the "Rebuild database" button.
To add a database to the "User Configuration Databases" list, click the "Add" button
and supply a suitable "Name" (E.g. Imported) and "Location" for the database.

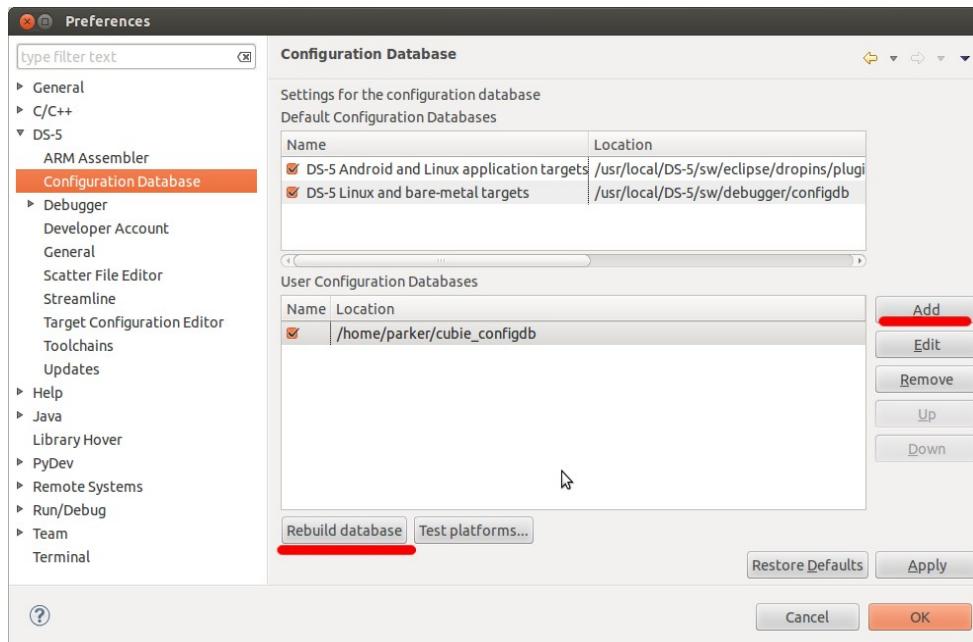
parker@parker:/work/tools/DS-5-Workspace$
```

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- 3) Start DS - 5, open the "Preferences" option under "Window" menu, a DS - 5 options, select "Configuration Database". Click "Add" button to add new configuration database.



As the same interface with the above , click "Rebuild the Database", to ensure that the new target Database load,then click "OK" to exit.

4. Using DSTREAM simulator debugging Android kernel

4.1. Add the kernel options

Description: We take the android kernel for example, the operation method of the Linux kernel are similar, need to pay attention to the path and the method of compilation.

Select a cubieboard kernel source code, execute “make ARCH = arm menuconfig ”.



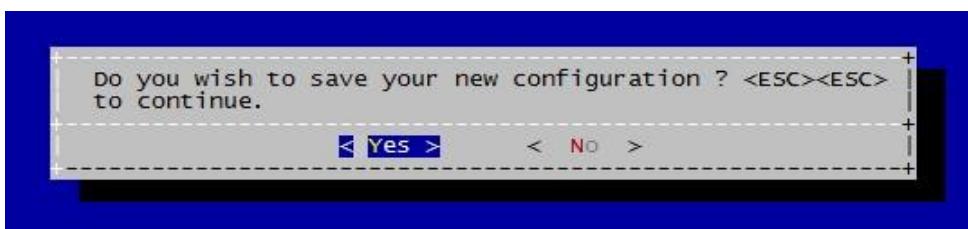
Choose “kernel hacking”>“Kernel debugging” option ,symbol is “DEBUG_KERNEL”.

```
+-----  
[ ] show timing information on printk  
(4) Default message log level (1-7)  
[*] Enable __deprecated logic  
[*] Enable __must_check logic  
(1024) Warn for stack frames larger than (needs gcc 4.4)  
[ ] Magic SysRq key  
[*] Strip assembler-generated symbols during link  
Generate readable assembler code  
[ ] Enable unused/obsolete exported symbols  
-**- Debug Filesystem  
[ ] Run 'make headers_check' when building vmlinux  
[ ] Enable full Section mismatch analysis  
-**- Kernel debugging  
    [ ] Debug shared IRQ handlers  
    [ ] Detect Hard and Soft Lockups  
    [ ] Panic on Ooops  
+-----  
v(+)
```

Choose “kernel hacking”>“compile the kernel with debug info” option, symbol is“DEBUG_INFO”.

```
+-----  
[ ] Mutex debugging: basic checks  
[ ] Lock debugging: detect incorrect freeing of live locks  
[ ] Lock debugging: prove locking correctness  
[ ] RCU debugging: sparse-based checks for pointer usage  
[ ] Lock usage statistics  
[ ] Sleep inside atomic section checking  
[ ] Locking API boot-time self-tests  
[ ] Stack utilization instrumentation  
[ ] Kobject debugging  
[*] Verbose BUG() reporting (adds 70K)  
[*] Compile the kernel with debug info  
    [ ] Reduce debugging information (NEW)  
    [ ] Debug VM  
    [ ] Debug filesystem writers count  
[*] Debug memory initialisation  
[ ] Debug linked list manipulation  
+-----  
v(+)
```

After Configurate,press two times, prompt exit select < Yes > save and exit.





4.2. Compile the kernel

After modify the kernel configuration, we need to recompile the kernel and generate vmlinux, and use to this file later.

Compile methods don't elaborate on here, please read:

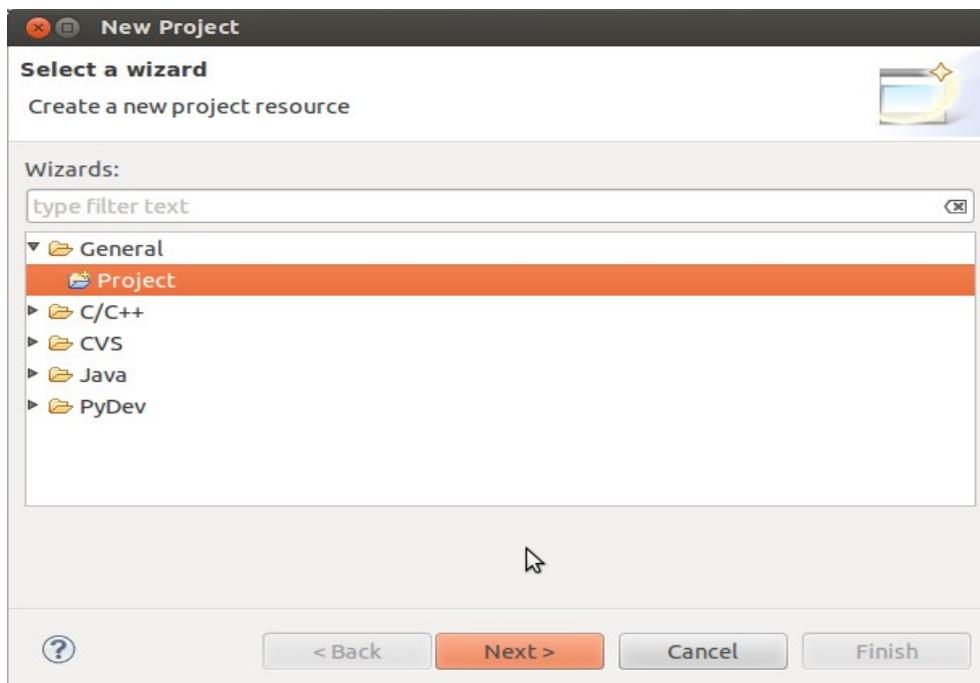
android: <http://pan.baidu.com/s/1dDF5cVR>

linux: <http://pan.baidu.com/s/1o6LYsDs>

4.3. Import the kernel source to DS - 5

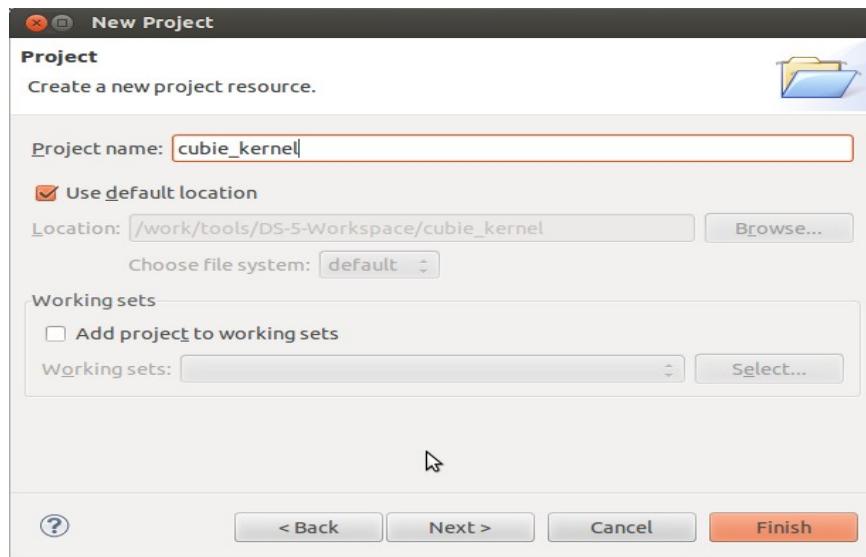
Create a new project in DS - 5, named "MYD - SAMA5D3X_kernel" ,import the kernel source code.

Open DS-5,choose “File” > “New” > “Project...”.

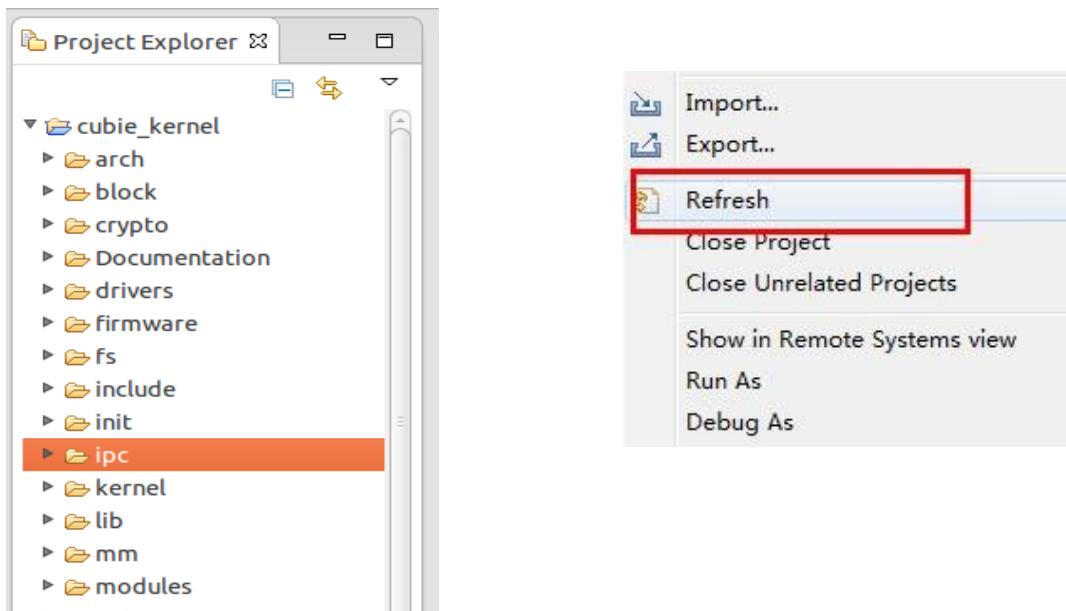




Input the project name in the “project name”, be named "cubie_kernel", then click "finish" to complete the project creation.



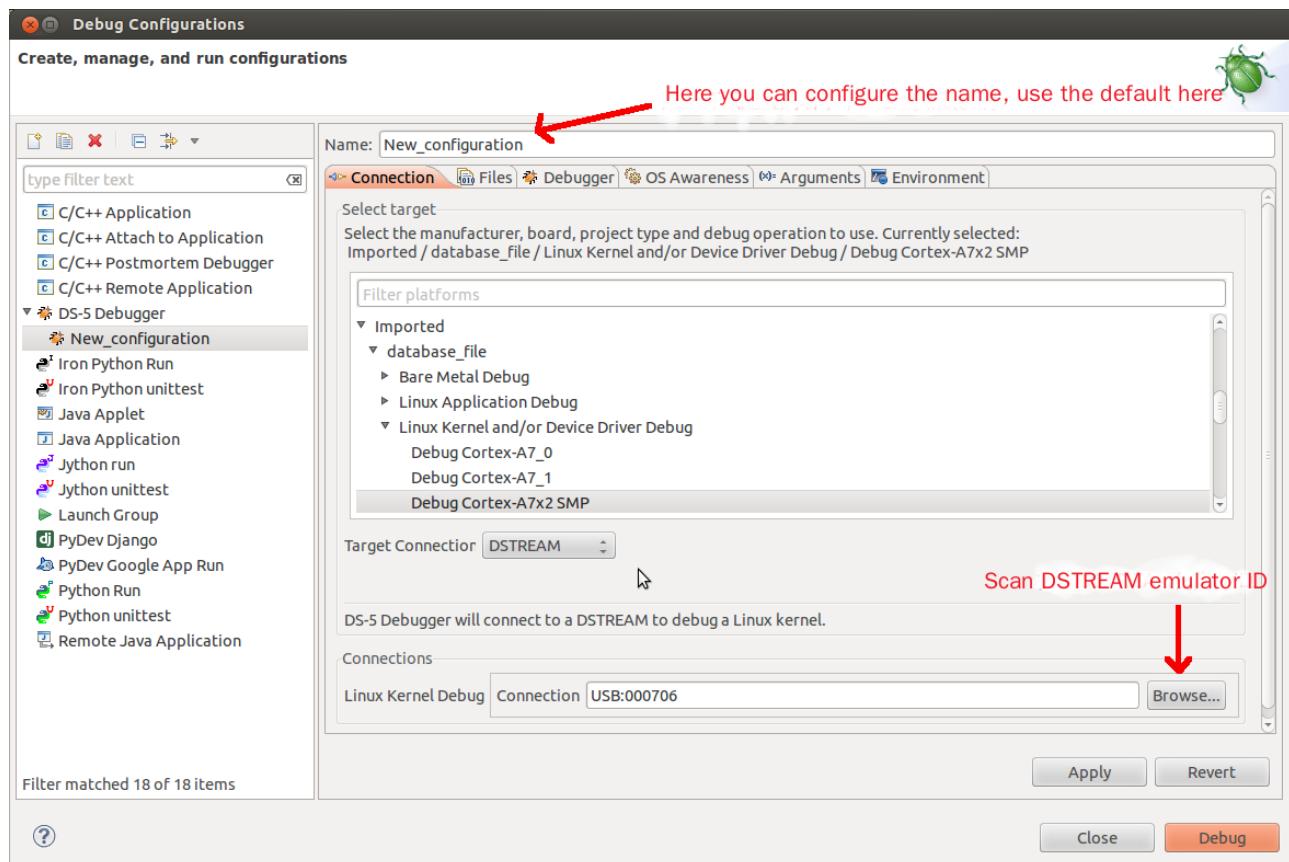
Copy all the contents of compiled to the project directory(example:cp -a /lichee/linux-3.4/* /work/tools/DS-5-Workspace/cubie_kernel),then right-click project name, select "Refresh" to Refresh. The add file of DS - 5 will be displayed.





4.4. Debug configuration

Open the menu bar "Run" > "the Debug Configurations..." , "DS - 5 Debugger" selected "New_configuration". Choose "Select target" > > "Imported" > "database_file" "Linux Kernel and/or Device Device Debug" > "Debug Cortex-A7x2 SMP"(red font is the database directory name for you create, please find according to actual situation).Target "connections" click "browse..." Select search to DSTREAM simulator.





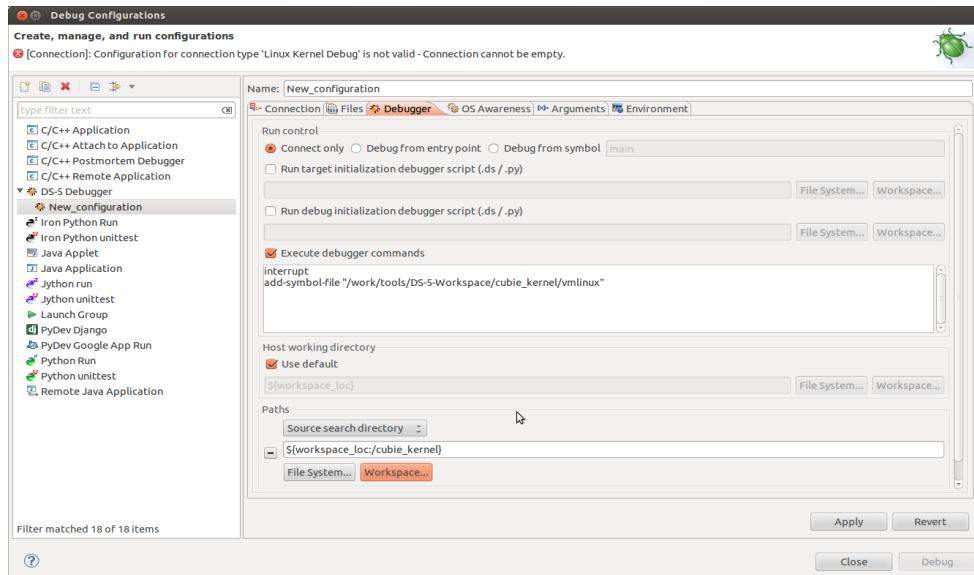
Configure "Debugger" option below ,operation control "Run control" select "connect only" .

Click on the "Execute the debugger commands" and input in the input box:

interrupt

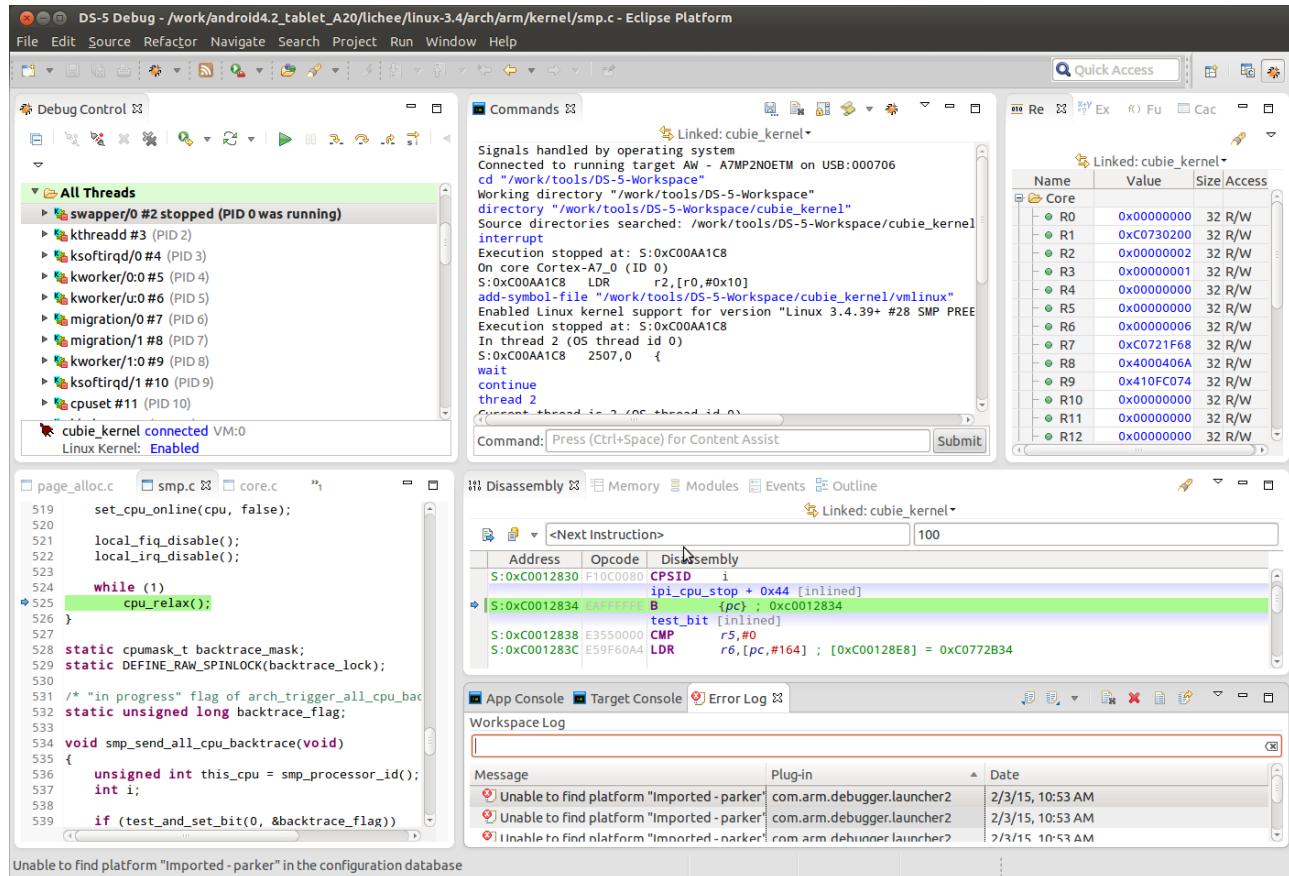
```
add-symbol-file "/work/tools/DS-5-Workspace/cubie_kernel/vmlinux"
```

Click on the "Workspace..." button below"Paths" ,choose "cubie_kernel" project as DS - 5 source search path.Open the cubietruck power (or reset), let u-boot guide the kernel, and then click the "Debug" button at the DS - 5 to start debugging.



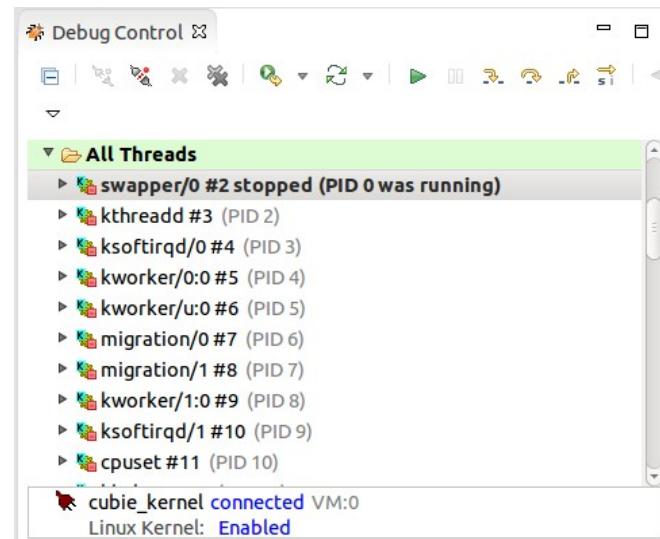


Finally, we will see an interface in the following . Represents the target plate and the simulator has been successfully connected, and you can start debugging.



4.5. Debug interface specification

The DS - 5 started to connect the development board, the view is as follows, all show the current name of debugging, and it can debug control.





In the figure above, the function of each control button as follows:

- USB: Connect plate
- USB: Disconnect
- X: Delete the connection
- Debug: From the main function or entry point debugging
- Run: Continue to run at full speed
- Stop: Stop running
- Single Step: Single step debugging
- Choose: Choose according to the C program on the basis of single step debugging or assembler debugging

Command bar which can input command after “commands”and make development board runing, such as input "step" would doing single step debugging . The mouse is located in the input box, press "Alt + /" can obtain the command prompt.

```
Commands >
Linked: cubie_kernel>
Signals handled by operating system
Connected to running target AW - A7MP2NOETM on USB:000706
cd "/work/tools/DS-5-Workspace"
Working directory "/work/tools/DS-5-Workspace"
directory "/work/tools/DS-5-Workspace/cubie_kernel"
Source directories searched: /work/tools/DS-5-Workspace/cubie_kernel
interrupt
Execution stopped at: S:0xC00AA1C8
On core Cortex-A7_0 (ID 0)
S:0xC00AA1C8 LDR r2,[r0,#0x10]
add-symbol-file "/work/tools/DS-5-Workspace/cubie_kernel/vmlinux"
Enabled Linux kernel support for version "Linux 3.4.39+ #28 SMP PREEMPT"
Execution stopped at: S:0xC00AA1C8
In thread 2 (OS thread id 0)
S:0xC00AA1C8 2507,0 {
wait
continue
thread 2
Current thread is 2 (OS thread id 0)
```

Command: Press (Ctrl+Space) For Content Assist



Assembler bar, display program corresponding the assembler, address and the operands, etc.

The screenshot shows the DS-5 debugger interface with the Assembler bar open. The code displayed is from the file smp.c, specifically the function smp_send_all_cpu_backtrace. The assembly code is shown in green, while the C code is in black. The assembly code includes instructions like 'set_cpu_online(cpu, false);' and a loop with 'cpu_relax();'. The C code includes static variables 'cpumask_t backtrace_mask' and 'DEFINE_RAW_SPINLOCK(backtrace_lock)', and a function definition for 'void smp_send_all_cpu_backtrace(void)'.

Register bar, shows all registers, the inside of the kernel, can be modify register when debugging

The screenshot shows the DS-5 debugger interface with the Registers bar open. The table lists the following registers and their values:

Name	Value	Size Access
R0	0x00000000	32 R/W
R1	0xC0730200	32 R/W
R2	0x00000002	32 R/W
R3	0x00000001	32 R/W
R4	0x00000000	32 R/W
R5	0x00000000	32 R/W
R6	0x00000006	32 R/W
R7	0xC0721F68	32 R/W
R8	0x4000406A	32 R/W
R9	0x410FC074	32 R/W
R10	0x00000000	32 R/W
R11	0x00000000	32 R/W
R12	0x00000000	32 R/W
SP	0x0000771EAn	32 R/W

About more detailed content, please refer to the document of the arm's official website:

<http://infocenter.arm.com/help/index.jsp>